

# **USER'S GUIDE**



# Vaisala HUMICAP® Moisture and Temperature Transmitter for Oil MMT162



M210934EN-D

#### PUBLISHED BY

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# CHAPTER 1 GENERAL INFORMATION

This chapter provides general notes for the manual and the product.

#### **About This Manual**

This manual provides information for installing, operating, and maintaining Vaisala HUMICAP<sup>®</sup> Moisture and Temperature Transmitter for Oil MMT162.

#### **Contents of This Manual**

This manual consists of the following chapters:

- Chapter 1, General Information, provides general notes for the manual and the product.
- Chapter 2, Product Overview, introduces the features, advantages, and the product nomenclature
- Chapter 3, Installation, provides you with information that is intended to help you install the product.
- Chapter 4, Operation, provides information that is needed in basic maintenance of the product.
- Chapter 5, Maintenance, provides information that is needed in basic maintenance of the product.
- Chapter 6, Calibration and Adjustment, provides information that is needed in calibration and adjustment of the product.
- Chapter 7, Technical data, provides the technical data of the product.
- Appendix A, Modbus Reference, describes the Modbus protocol implementation of the MMT162 transmitter.

#### **Version Information**

Table 1	Manual	Revisions
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Manual Code	Description
M210934EN-D	October 2014. This manual. Applicable from software version 1.10 onward. Added Modbus protocol. Updated descriptions of serial commands. Updated calibration and adjustment instructions. Updated list of spare parts and accessories.
M210934EN-C	April 2013. Updated descriptions of connection cables and serial line commands. Updated list of spare parts and accessories.
M210934EN-B	March 2009. Updated cable specification.

#### **Related Manuals**

Table 2Related N	Related Manuals	
Manual Code	Manual Name	
M210935EN	MMT162 Quick Reference Guide	

#### **Documentation Conventions**

Throughout the manual, important safety considerations are highlighted as follows:

death.	<b>WARNING</b> Warning alerts you to a serious hazard. If you do not read and follow instructions very carefully at this point, there is a risk of injury or ever death.	
--------	--	--

**CAUTION** Caution warns you of a potential hazard. If you do not read and follow instructions carefully at this point, the product could be damaged or important data could be lost.

**NOTE** Note highlights important information on using the product.

# Safety

The Vaisala HUMICAP<sup>®</sup> Moisture and Temperature Transmitter for Oil MMT162 delivered to you has been tested for safety and approved as shipped from the factory. Note the following precautions:

WARNING	Ground the product, and verify outdoor installation grounding periodically to minimize shock hazard.
CAUTION	Do not modify the unit. Improper modification can damage the product

# Recycling



Recycle all applicable material.

or lead to malfunction.



Dispose of batteries and the unit according to statutory regulations. Do not dispose of with regular household refuse.

### **Regulatory Compliances**

Vaisala HUMICAP<sup>®</sup> Moisture and Temperature Transmitter for Oil MMT162 is in conformity with the following EU directive:

- EMC-Directive

Conformity is shown by compliance with the following standards:

- EN 61326-1: Electrical equipment for measurement, control and laboratory use EMC requirements Industrial environment.
- EN 55022 Class B: Information technology equipment Radio disturbance characteristics Limits and methods of measurement.

# CE

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#### Warranty

Visit our Internet pages for standard warranty terms and conditions: <u>www.vaisala.com/warranty</u>.

Please observe that any such warranty may not be valid in case of damage due to normal wear and tear, exceptional operating conditions, negligent handling or installation, or unauthorized modifications. Please see the applicable supply contract or Conditions of Sale for details of the warranty for each product.

# CHAPTER 2 PRODUCT OVERVIEW

This chapter introduces the features, advantages, and the product nomenclature of Moisture and Temperature Transmitter for Oil MMT162.

#### **Introduction to MMT162**

The MMT162 transmitter is a microprocessor based instrument for the measurement of moisture in terms of water activity, for example in the lubrication of circulation systems or in transformer oil. The probe incorporates a capacitive thin film sensor. The operation of the sensor is based on changes in its capacitance as the thin polymer film absorbs water molecules.

The MMT162 transmitter is available with either metal or plastic housing. The transmitter can be configured in many ways: two analog output signals can be scaled, the measurement ranges can be changed within certain limits and there are two mechanical connection options, ISO and NPT 1/2. The MMT162 probe is supplied with a three or five meter connection cable.

The MMT162 also provides for accurate temperature measurement. It is an easy-to-install on-line probe which can be calibrated against, for example, traceable salt solutions.

Table 5         Parameters measured and Calculated by MINIT 102			
Parameter	Abbreviation	Metric Unit	Non Metric Unit
Water activity	A <sub>w</sub>		
Temperature	Т	°C	°F
Mass concentration of water in oil	H <sub>2</sub> O	ppm	ppm

Table 3Parameters Measured and Calculated by MMT162

**NOTE** ppm is only applicable to transformer oil.

Vaisala HUMICAP<sup>®</sup> Moisture and Temperature Transmitter for Oil MMT162 provides reliable moisture measurement in wide range of applications. Analog outputs can be chosen between current and voltage signals. Alternatively, digital output RS-485 comes as standard.

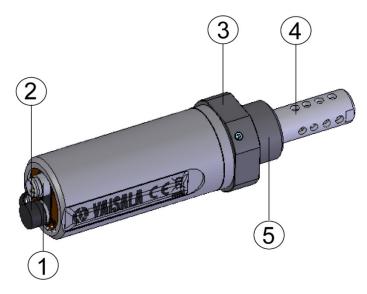
### **Basic Features and Options**

- Two analog outputs
- Digital output: RS-485 with onboard Modbus protocol
- USB connectivity for service connections via the optional USB M8 cable
- Different cable lengths available
- Available with two different thread options: ISO G1/2" and NPT 1/2"
- Low maintenance requirements due to excellent long term stability
- LED cable option that enables a visual alarm function
- Field calibration possible with MM70
- Two filter types available: stainless steel grid filter and high flow stainless steel grid filter (> 1 m/s)

#### **Transmitter Structure**

The structure of the MMT162 is shown in Figure 1 on page 11. The transmitter body does not have user serviceable parts inside, and is not designed to be opened. Opening the transmitter will void the warranty.

When the transmitter is delivered, the filter is protected by a yellow transport protection cap. Remove the transport protection cap before installing the transmitter.



0805-007

# Figure 1 Moisture and Temperature Transmitter for Oil MMT162

where

- 1 = 4-pin M8 connector I: analog output channels and operating power
- 2 = 4-pin M8 connector II (shown with protective cap): digital output (RS-485) and operating power
- 3 = 30 mm nut
- $4 = HUMICAP^{\text{®}}$  sensor protected with stainless steel grid filter
- 5 = Connection thread: ISO G1/2" or NPT 1/2"

### **Typical Applications**

# Method Used for Measuring Moisture in Oil

The MMT162 transmitter measures water in oil in terms of water activity (aw) which can be determined as follows: water activity indicates the amount of water on the scale of 0 - 1 aw. In this scale, 0 aw is an indication of completely water free oil and 1 aw an indication of oil fully saturated with water. Water is present in free form.

The most important feature which distinguishes the measurement of water activity (aw) from the traditional measurement of absolute water content (in ppm) is that the saturation point remains stable regardless of the oil type or the aging of oil, additives used etc. As water activity exceeds 0.9 aw in any system, there is a risk for segregation (especially if the temperature decreases).

The water activity is used for alarming at the point of >0.9 aw that the risk for free water in the system is obvious. The most important advantages of this system are the fact that water activity is immune to the aging of oil and to additives, and that the MMT162 transmitter can be used for continuous on-line measurements. In addition, the MMT162 can be calibrated against salt solutions and no reference oils are needed.

#### NOTE

To avoid self-heating of the probe and consequential measurement errors, make sure there is some flow in the application process.

#### **Lubrication Oil**

In many industrial plants, like paper mills, hydro power plants and offshore wind turbines, there is a certain amount of free moisture constantly present. This means that there is a high risk of the free moisture becoming into contact with the machine bearings. The most common reasons for the entrance of water are inadequate sealing of the housing or moisture absorption from ambient air. Accidental leakages from oil coolers and other equipment can also cause damage.

Free water in lubrication oil prevents oil from forming a uniform layer on the metal surfaces and thus deteriorating its lubrication properties. This can cause, for example, spot heating, cavitation, corrosion and micro pitting. Free water also ruins additives like AW (antiwear) and EP (extreme pressure). Note that bearings should never be exposed to oils that have high water content; this is also important during standstill because the risk for corrosion increases as the oil temperature decreases. It is essential to monitor the water content and to keep it on a suitable level, meaning below saturation.

When measuring the water content of oil, it is best to measure the water activity before an oil reservoir and from a pressure line flow. This way the performance of dehumidifiers can be kept under control to ensure that no free water reaches the bearings.

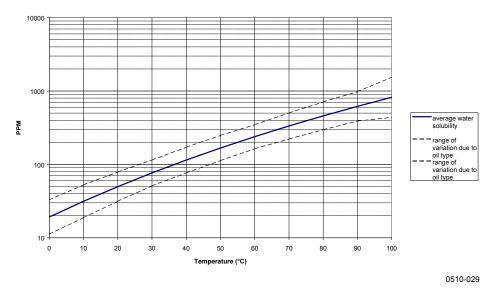
#### **Transformer Oil**

The determination of moisture in oil is an essential part of a comprehensive transformer maintenance program. Aging and deterioration increase the capacity of oil to absorb water. The primary interest in transformers is to measure the water not in oil but in the cellulosic insulation around the transformer windings. Heating and cooling have a considerable effect on moisture levels in oil. While temperature rises, the paper insulation of transformers tends to loose moisture which is absorbed by the oil surrounding it. Saturation level is thus a true indicator of moisture present. The MMT162 method provides for a reliable detection of the aging of oil and possible leakages.

Oil immersed transformers rely on the oil for cooling, protection from corrosion and as an important component of their insulation. Excessive moisture content in oil causes accelerated ageing of the insulation materials and reduces their dielectric strength. In extreme cases this can result in arcing and short circuits within the windings. Accurate moisture measurements can also warn about leaks in the oil system, as water is absorbed from the surrounding air.

Heating and cooling of a transformer affect moisture levels in oil. This is due to the fact that the water solubility of oil is temperature dependent. In general, water solubility increases as temperature rises; see Figure 2 on page 14 below. Changes in temperature also have an effect on water desorption of the paper insulation around the transformer windings. Desorption of water from the insulation increases as temperature rises and the surrounded oil absorbs desorbed water. Moisture level in oil is thus a true indicator of moisture present in the paper insulation.

In addition, it must be noted that capacity of oil to absorb water depends both on the chemical structure of the oil and the additives. WATER SOLUBILITY IN MINERAL TRANSFORMER OIL



#### Figure 2 Water Solubility of Transformer Oils versus Temperature

The margins show the range of variation of water solubility found in mineral oils.

# CHAPTER 3

This chapter provides you with information that is intended to help you install the product.

#### **Installing the Transmitter**

After selecting a suitable measurement location, follow the procedure below to install the transmitter:

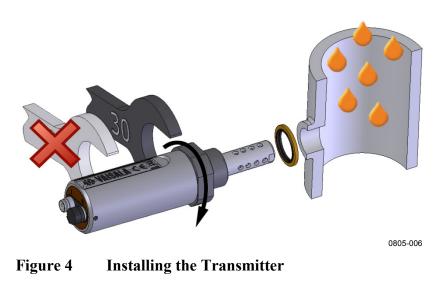
1. Remove the yellow transport protection cap from the transmitter.



0805-005

Figure 3 Removing the Transportation Protection Cap

- 2. Prepare the sealing of the connection:
  - If the transmitter has a parallel ISO G1/2" thread, place the sealing ring at the base of the thread. Always use a new sealing ring; do not re-use a previously installed one.
  - If the transmitter has an NPT 1/2" thread, do not use the sealing ring. Instead, apply PTFE tape or suitable paste sealant to the thread. Follow the application instructions of the sealant.
- 3. Make sure that the threads on the mounting point are of the correct type, and fasten the transmitter to the measurement point. Use your hands to turn the probe until it feels tight. Do not use force at this point, and check that the sealing ring (if used) remains centered.



4. Use a 30 mm wrench to tighten the connection to 25 Nm, as shown in Figure 4 above. If you do not have a 30 mm wrench, use a 1 3/16" wrench or an adjustable wrench instead.

**CAUTION** Only tighten the probe from the 30 mm nut. Do NOT apply force to other points in the probe body.

5. Connect the wires of the connection cable.

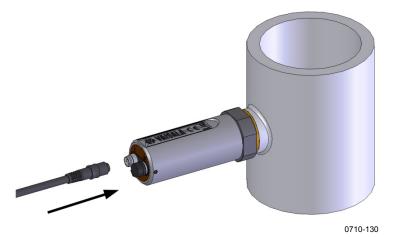
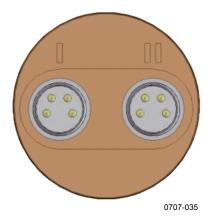


Figure 5 Connecting the Cable

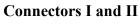
- 6. Plug in the cable to the transmitter. Be sure to use the correct connector; refer to section Wiring on page 17.
- 7. Cover the unused connector on the transmitter with the rubber plug that is attached to the transmitter.

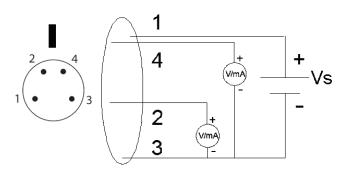
# Wiring

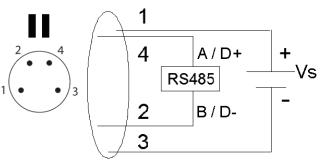
Pin	I	II	Wire Color
1	Vcc	Vcc	Brown
2	Analog output 1	RS-485 B / D-	White
3	GND	GND	Blue
4	Analog output 2 / LED	RS-485 A / D+	Black











1210-005



#### **Connection Cables**

The following connection cable options are available for MMT162:

- Shielded cables with M8 female straight threaded connector
- Cables with M8 female 90° angle threaded connector
- LED cable
- USB serial interface cable

The figures below show the different cable options that are available. For order codes, see section Spare Parts and Accessories on page 67.



Figure 8 Cable with Threaded Connector



Figure 9 Cable with 90° Angle Threaded Connector



Figure 10 LED Cable



Figure 11USB Serial Interface Cable

#### **Power Supply Requirements**

The MMT162 transmitters are designed to operate with a supply voltage of  $14 \dots 24$  VDC.

The power supply should maintain the voltage for all load conditions. Current consumption during normal measurement is 20 mA + load current. For more specific information, see chapter Technical data on page 65.

# CHAPTER 4 OPERATION

This chapter contains information that is needed to operate this product.

#### **Transmitter Start-Up**

When the transmitter is connected to power supply, there is a delay of five seconds as the transmitter starts up. After the start-up is complete, the measurement data is available from the analog outputs or serial line.

If serial line output is used, note that the transmitter will behave according to the configured serial mode:

- In STOP mode, the transmitter outputs the transmitter model and software version. This is the default mode.
- In RUN mode, a measurement output starts immediately.
- In POLL mode, the transmitter does not output anything after power-up.
- In MODBUS mode, the transmitter does not output anything after power-up.

For a description of the modes, see section Set Serial Interface Mode on page 33.

#### **Analog Output Operation Modes**

The MMT162 has two analog output channels. These channels can function in two different modes, which can be set individually for both channels:

- 1. Normal operation mode
- 2. Limit alarm mode

When the transmitter is ordered from Vaisala, the modes are configured as specified in the order form. You can change the operation settings after delivery by using serial commands and the USB cable accessory.

# Normal Operation Mode and Malfunction Alarm

In the normal operation mode, a channel outputs voltage or current that corresponds to the reading of the selected parameter.

If the transmitter is malfunctioning, the channel output is set to a predefined level. This level can be changed using the **AERR** command; see page 35.

# **NOTE** The malfunction alarm overrides the limit alarm mode. If the transmitter is malfunctioning, the analog outputs are set to the levels specified with the **AERR** command, unless the malfunction prevents the outputs from being controlled.

#### Limit Alarm

The limit alarm is activated when the measured parameter goes below the low limit, or above the high limit. The alarm levels and limits are configurable using the **ALARM** command (see page 36). By default, the alarm levels are set as follows:

- For **current output**, an active alarm is indicated by the current being at the maximum of the scale (20 mA).
- For **voltage output**, an active alarm is indicated by the voltage being at the maximum of the selected scale. For example, if the voltage output scale is 0 ... 5 V, an output of 5 V indicates the alarm is active.
- For **LED alarm**, an active alarm is indicated by a lit LED. When the alarm status is low, the LED is not lit. If the transmitter is malfunctioning or it cannot measure for some reason, this causes the LED to blink at 0.5 Hz frequency.

LED alarm indicator is integrated to a LED cable (Vaisala item MP300LEDCBL) that can be ordered and used instead of a regular connection cable.

### **Serial Communication**

#### **Connecting to Serial Interface**

The MMT162 can be connected to a PC using the RS-485 line, for example using the USB serial connection cable (Vaisala item 219690). The cable also provides operation power to the transmitter from the USB port. It is OK to connect the USB serial connection cable even if the transmitter is already supplied with operation power from another cable.

To connect to serial interface:

- 1. If you have not used the MMT162 USB serial connection cable before, install the driver that came with the cable. Refer to section Installing the Driver for the USB Cable on page 23 for detailed instructions.
- 2. Connect the USB serial connection cable between your PC and the RS-485 port of the MMT162 (port II).
- 3. Open the terminal program (for example, PuTTY in Microsoft Windows<sup>®</sup>).
- 4. Set the serial settings of the terminal program, and open the connection. See the following table.

Property	Description / Value	
Baud rate	19200	
Parity	none	
Data bits	8	
Stop bits	1	

Table 4Default Serial Interface Settings

If the MMT162 is in Modbus mode, to access the serial port command interface, follow the procedure in Accessing Serial Port Command Interface from Modbus Mode on page 44.

#### Installing the Driver for the USB Cable

Before taking the USB cable into use, you must install the provided USB driver on your PC.

- 1. Check that the USB cable is not connected. Disconnect the cable if you have already connected it.
- 2. Insert the media that came with the cable, or download the driver from <u>www.vaisala.com</u>.
- 3. Execute the USB driver installation program and accept the installation defaults. The installation of the driver may take several minutes.
- 4. After the driver has been installed, connect the USB cable to a USB port on your PC. Windows will detect the new device, and use the driver automatically.
- The installation has reserved a COM port for the cable. Verify the port number, and the status of the cable, using the Vaisala USB Instrument Finder program that has been installed in the Windows Start menu.

Windows will recognize each individual cable as a different device, and reserve a new COM port. Remember to use the correct port in the settings of your terminal program.

#### **Terminal Program Settings**

The default settings of the MMT162 serial interface are presented in Table 4 on page 22. If the settings of your MMT162 have been changed and you do not know what they are, refer to section Unknown Serial Settings on page 52.

The steps below describe how to connect to the MMT162 using the PuTTY terminal application for Windows (available for download at <u>www.vaisala.com</u>) and a USB serial interface cable:

- 1. Connect the USB serial interface cable between your PC and the RS-485 port of the MMT162 (port II).
- 2. Start the PuTTY application.
- 3. Select the **Serial** settings category, and check that the correct COM port is selected in the **Serial line to connect to** field.

Note: You can check which port the USB cable is using with the **Vaisala USB Instrument Finder program** that has been installed in the Windows Start menu.

- 4. Check that the other serial settings are correct for your connection, and change if necessary. **Flow control** should be set to **None** unless you have a reason to change it.
- 5. Click the **Open** button to open the connection window and start using the serial line.

Note: If PuTTY is unable to open the serial port you selected, it will show you an error message instead. If this happens, restart PuTTY and check the settings.

6. You may need to set the Local echo setting to Force on in the Terminal category to see what you are typing on the serial line. To access the configuration screen while a session is running, click the right mouse button over the session window, and select Change Settings... from the pop-up menu.

If the MMT162 is in Modbus mode, to access the serial port command interface, follow the procedure in Accessing Serial Port Command Interface from Modbus Mode on page 44.

🔀 PuTTY Configuration		? 🛛
Category:		
Session     Terminal     Window     Connection     Ota     Proxy     Telnet     Rlogin	Options controlling local set Select a serial/USB line Serial or USB line to connect to Configure the serial/USB line	COM3
Serial & USB	<u>Speed (baud)</u> Data <u>bits</u> Stop bits Parity Flow control	8 1 None 🗸
About <u>H</u> elp		n <u>C</u> ancel

Figure 12 PuTTY Terminal Application

#### **List of Serial Commands**

All commands can be issued either in uppercase or lowercase. In the command examples, the keyboard input by the user is in **bold** type.

The notation <cr> refers to pressing the carriage return (**Enter**) key on your computer keyboard. Enter a <cr> to clear the command buffer before starting to enter commands.

Table 5   Serial Line Commands			
Command	Description		
?	Output information about the device		
??	Output information about the device in		
	POLL mode		
ACAL	Analog output calibration		
ADDR <b>[0</b> 255]	Set the transmitter address (for POLL		
	mode)		
AERR	Change the analog error output values		
ALARM	Set analog output limit alarm modes		
AMODE	Set analog output modes		
AOVER [ON/OFF]	Allow analog outputs to exceed their range 10%		
ASEL	Select the parameters for the analog		
	outputs		
ATEST	Set and display current output values		
CLOSE	Close the temporary connection (Back to		
	POLL mode)		
CRH	Relative humidity calibration		
СТ	Temperature calibration		
ERRS	List present transmitter errors		
FORM	Set the output format of SEND and R		
	commands		
FRESTORE	Restore factory settings		
HELP	List the most common commands		
INTV [ <b>0</b> 255 <b>S</b> /MIN/H]	Set the continuous output interval		
	(for RUN mode)		
L	Show user calibration coefficients		
LED	Set voltage for LED alarm		
OIL	Display oil parameters		
OILI	Set new oil parameters		
OPEN <b>[0</b> 255]	Open a temporary connection to a POLL		
	mode device		
R	Start the continuous outputting		
RESET	Reset the transmitter		
S	Stop the continuous outputting		
SDELAY	View or set user port (RS-485) answer		
	minimum delay		
SEND [0 255]	Output the reading once		
SERI [baud p d s]	User Port settings (Default: 4800 E 7 1)		
	baud: 300 115200		
SMODE	Set the serial interface mode		
[STOP/RUN/POLL/MODBUS]	Coloct the metric or non-metric output units		
UNIT [M/N]	Select the metric or non-metric output units		
VERS	Display the software version information		

Table 5Serial Line Commands

#### **Device Information and Status**

#### **Show Device Information**

The ? command outputs a listing of device information. If you wish to display the listing for all devices on the current serial line, issue the command ??.

?<cr>

??<cr>

#### **Example:**

?		
MMT162 0.92		
Serial number	:	G000002
Batch number	:	D0720012
Module number	:	????????
Sensor number	:	C6010000
Sensor model	:	Humicap L2
Cal. date	:	YYYYMMDD
Cal. info	:	NONE
Time	:	00:21:19
Serial mode	:	STOP
Baud P D S	:	4800 E 7 1
Output interval	:	2 S
Serial delay	:	0
Address	:	0
Pressure	:	1.0132 bar
Filter	:	0.800
Chl output	:	0 20 mA
Ch2 output	:	0 20 mA
Ch0 error out	:	0.000 mA
Chl error out	:	0.000 mA
Ch0 aw lo	:	0.00
Ch0 aw hi	:	1.00
Ch1 T lo	:	-20.00 'C
Ch1 T hi	:	80.00 'C

#### **Show Firmware Version**

Use the VERS command to display software version information.

Example:

**vers** MMT162 1.02

## **Configuring Serial Line Operation**

#### **Set Serial Line Settings**

Use the serial line command **SERI** [b p d s] to set communication settings for the user port.

Bit rates less than 9600 b/s are not supported with Modbus.

**SERI** [b p d s] < cr >

where

- b = Bit rate (110, 150, 300, 600, 1200, 2400, 4800, 9600, 19200, 38400)
- p = Parity (n = none, e = even, o = odd)
- d = Data bits (7 or 8)
- s = Stop bits (1 or 2)

Example:

```
seri 600 n 8 1
600 N 8 1
```

You need to reset the transmitter to activate the new communication settings set with the **SERI** command.

The settings can be changed one parameter at a time or all parameters at once:

<b>seri o</b> 4800 O 7 1	changing parity only
<b>seri 600 n 8 1</b> 600 N 8 1	changing all parameters

You can use the **SERI** command to change/view the user port settings even if you are currently connected to the service port.

#### Set Serial Line Response Time

With the **SDELAY** command you can set delay (response time) of the serial line, or view the currently set delay value.

SDELAY [delay]<cr>

where

*delay* = Serial line delay, range 0 ... 255. Multiply the value by four to get milliseconds (for example, delay value of 10 equals 40 millisecond delay).

Example:

sdelay
Serial delay : 0 ? 10
sdelay
Serial delay : 10 ?

#### Set Transmitter Address

Addresses are required only for POLL mode (see Set Serial Interface Mode on page 33). Use the **ADDR** command to input the RS-485 transmitter address.

#### ADDR [aaa]<cr>

where

 $aaa = address (0 \dots 255) (default = 0)$ 

Example (configure transmitter to address 99):

addr Address : 2 ? 99

#### **Format Measurement Output**

Use the serial line command **FORM** to change the format or select certain parameters for the output commands **SEND** and **R**.

FORM [x] < cr >

where

x = Formatter string

Formatter string consists of parameters and modifiers. The MMT162 measures the following parameters:

- water activity (aw)
- temperature (T) (metric unit: °C, non metric unit: °F)
- ppm for transformer oil only (H<sub>2</sub>O)

When selecting the parameter, use its abbreviation (for example, aw). The modifiers are presented in Table 6 on page 31.

Example (configure transmitter to output water activity and temperature):

```
form "aw=" 6.4 aw #t "t=" 6.2 t #r#n
OK
send
aw= 0.2644 t= 25.50
```

Example (configure transmitter to output ppm only):

form "Oil ppm= " h2o " " u3 #r#n
OK
send
Oil ppm= 16.6 ppm

Example (configure transmitter to default output format):

form / OK send aw= 0.087 T= 24.0 'C

Table 6	FORM Command Modifiers
Modifier	Description
/	Restores the default output message (depends on the
	device configuration). Used alone.
x.y	Length modifier (number of digits and decimal places).
parameter	Abbreviation of a measured parameter, for example aw.
	Outputs the measured value of the parameter, or
	* characters if measured value is not available.
U1U7	Unit symbol in the specified number of characters
	(truncated or space filled as necessary).
"XXX"	String constant (free text).
#a	Audible bell character <07h>.
\a	
#b	Backspace character <08h>
\b	
#f	Form feed character <0Ch>.
\f	
#n	Line feed character <0Ah>.
\n	
#r	Carriage return character <0Dh>.
\r	
#t	Horizontal tabulator character <09h>.
\t	
#v	Vertical tabulator character <0Bh>.
\v	
#\	Backslash character.
//	
#0#255	Data byte with the specified decimal value.
\0\255	
ADDR	Device address (left-filled with spaces).
CS2	Modulus-256 checksum of message sent so far,
	hexadecimal format.
CS4	Modulus-65536 checksum of message sent so far,
	hexadecimal format.
CSX	NMEA XOR checksum of message sent so far, hexadecimal
	format
ERR	Currently active transmitter errors in a four bit field.
	0 = no error, 1 = error.
	bit1 = Temperature measurement (T meas error)
	bit2 = Not used
	bit3 = Humidity measurement (F meas error)
	bit4 = Internal error (Program flash check sum error)
SN	Device serial number.
TIME	Time since transmitter startup in format hh:mm:ss.

Table 6FORM Command Modifiers

Checksums are calculated as described in the equations below.

$$1 = cs_{2} = \sum_{i=1}^{n} b_{i} \mod 256$$
  

$$2 = cs_{4} = \sum_{i=1}^{n} b_{i} \mod 65536$$
  

$$3 = cs_{x} = b'_{1} \oplus b'_{2} \oplus \dots \oplus b'_{n}$$
  

$$b'_{i} = b_{i} \text{ if } b_{i} \neq 36 \text{ and } b_{i} \neq 42$$
  

$$b'_{i} = 0 \text{ if } b_{i} = 36 \text{ or } b_{i} = 42$$

#### Table 7Symbols Used in FORM Checksum Equations

Symbol	Description
CS <sub>2</sub>	Value of CS2 checksum in the output message.
CS <sub>4</sub>	Value of CS4 checksum in the output message.
CS <sub>x</sub>	Value of CSX checksum in the output message.
b <sub>i</sub>	Value of the byte at position <i>i</i> (1-based) in the output message.
n	Number of bytes in the output message before the CS2, CS4, or CSX field (including earlier checksum fields, if any).
$\oplus$	Bit-wise exclusive-or operator.
36	Byte value of ASCII \$ character.
42	Byte value of ASCII * character.

#### **Select Unit**

Use the UNIT command to select metric or non-metric output units.

UNIT [x] < cr >

where

x = M or N

where

М	=	Metric units
Ν	=	Non-metric units

#### **Set Serial Interface Mode**

Use the SMODE command to set the default serial interface mode.

SMODE [xxxx]<cr>

where

xxxx =STOP, RUN or POLL

Table 8	<b>Output Modes</b>	
Mode	Measurement Output	Available Commands
STOP	Only with the <b>SEND</b> command.	All (default mode).
RUN	Automatic output.	Only command <b>S</b> .
POLL	Only with the <b>SEND</b> [ <i>addr</i> ] command.	SEND [addr] and OPEN [addr]. Other commands available after opening a line to the transmitter using the OPEN command. Use with RS-485 buses where multiple transmitters can share the same line.
MODBUS	Must be read from the transmitter using Modbus protocol.	Modbus protocol only; see Appendix A, Modbus Reference on page 70.

When several transmitters are connected to the same line, each transmitter must be entered an own address in the initial configuration, and POLL mode must be used.

If the Modbus mode is activated, serial port commands cannot be used with the device. To access the serial port command interface, follow the procedure in Accessing Serial Port Command Interface from Modbus Mode on page 44.

#### **Configuring Measurement Parameters**

# Select Analog Output Parameter and Scaling

Select and scale the parameters for the analog outputs with the **ASEL** command. Note that the optional parameters can be selected only if they have been selected when ordering the device.

#### ASEL [xxx yyy]<cr>

where

xxx = Parameter of channel 1 yyy = Parameter of channel 2

Always enter all the parameters for all outputs. The MMT162 measures the following parameters:

- water activity (aw)
- temperature (T) (metric unit: °C, non metric unit: °F)
- ppm for transformer oil only (H<sub>2</sub>O)

Example:

asel						
Ch0	aw	10	:	0.00	?	
Ch0	aw	hi	:	1.00	?	
Ch1	Т	10	:	-20.00	'C	?
Ch1	Т	hi	:	80.00	'C	?

#### Set Analog Output Mode (mA/V)

The **AMODE** command can be used to change the analog output mode of channels 1 and 2. When used without parameters it displays the current settings and with parameters new settings can be set. The available parameters are listed in Table 9 below.

Table 9Analog Output Modes

Parameter	Output mode
1	0 20 mA
2	4 20 mA
4	0 5 V
5	0 10 V
6	LED alarm
7	Current alarm
8	Voltage alarm

Example:

amoc	le 12				
Ch1	output	:	0	 20	mΑ
Ch2	output	:	4	 20	mΑ

### **Calibrate Analog Output**

Use the ACAL command to adjust analog output channels.

ACAL [channel]<cr>

where

channel = Analog output channel to be adjusted, 1 or 2.

After entering the ACAL command, use a calibrated current/voltage meter to measure the output, and enter the values.

Example:

```
      acal 1

      Ch1
      U1 (V) ? 1.001

      Ch1
      U2 (V) ? 9.011

      acal 2

      Ch2
      U1 (V) ? 0.0988

      Ch2
      U2 (V) ? 0.8997
```

## Set Malfunction Alarm Output for Analog Channels

Use the **AERR** command to set the analog output levels that are output in case of a device malfunction. The default output level is 0.

#### AERR<cr>

Example:

```
aerr
Ch1 error out : 10.000V ? 0
Ch2 error out : 1.000V ? 0
```

**NOTE** The error output value must be within a valid range of the output mode.

## **NOTE** The error output value is displayed only when there are minor electrical faults such as a humidity sensor damage. When there is a severe device malfunction, the error output value is not necessarily shown.

## Set Alarm Limits and LED Indication for Analog Outputs

Use the **ALARM** command to set the analog output alarm limits and parameters. For an explanation of the alarm limits, see section Limit Alarm on page 21.

#### ALARM<cr>

Before setting the alarm limits, verify the currently set analog output modes using the **AMODE** command.

The following example shows that a high limit alarm has been enabled for channel 2. If the measured value rises above the limit ( $0.90 a_w$ ), an error is reported. If you are using a LED cable, the LED lights up to indicate an error state.

Example:

#### alarm ?

Channel 1:		
Low Limit	:	OFF
High Limit	:	OFF
Aerr	:	ON
Quantity	:	Т
Limit Lo	:	15.00
Limit Hi	:	30.00
Hysteresis	:	0.50
Level Lo	:	0.20
Level Hi	:	0.80
Channel 2:		
Low Limit	:	OFF
High Limit	:	ON
Aerr	:	OFF
Quantity	:	aw
Limit Lo	:	0.10
Limit Hi	:	0.90
Limit Hi Hysteresis	:	0.90 0.01
	:	

### Set Voltage for LED Alarm

With the **LED** command, you can set a different voltage level for each channel.

LED<cr>

Example:

```
led ?
Ch 1 Led Voltage : 2.80 V
Ch 2 Led Voltage : 2.80 V
```

## **Extend Analog Output Range**

Use the **AOVER** command to allow the analog output channels to exceed their specified range by 10 %. The scaling of the parameter remains as before; the extra range is used for additional measurement range in the wet end.

```
AOVER [ON/OFF]<cr>
```

Example:

aover on : ON

## **Serial Line Output Commands**

### **Start Measurement Output**

Use the **R** command to start the continuous outputting of measurement values as an ASCII text string to the serial line. The format of the measurement message is set with the **FORM** command.

R<cr>

Example:

**r** aw= 0.261 T= 23.8 'C H2O= 15 ppm

You can change the format of the output with the following commands:

- Outputting interval can be changed with the INTV command.
- Output message format can be changed with the FORM command.

### **Stop Measurement Output**

Use the **S** command to end the RUN mode. After this command all other commands can be used. You can also press the **Esc** button or reset the transmitter to stop the outputting.

S<cr>

Since the interface is half-duplex, you must enter the command when the transmitter is not outputting. Give the command again if the transmitter continues to output measurement messages.

See **SMODE** command on page 33 to change the default (power-up) operation mode.

## Set Output Interval

Use the INTV command to set or display the output interval.

```
INTV [n xxx] < cr >
```

where

n	=	time interval = $0 \dots 255$
XXX	=	time unit = "S", "MIN", or "H"

Example:

```
intv 1 min
Output interval: 1 MIN
```

The shortest output interval (with n = 0) is approximately one second due to the internal measurement cycle.

## **Output Reading Once**

Use the SEND command to output the reading once in STOP mode.

The output format depends on which parameters the transmitter can output.

SEND [aaa]<cr>

where

aaa = Transmitter address (0 ... 255). Must be specified if the transmitter is in POLL mode, and a line has not been opened using the **OPEN** command.

Example:

```
send
T= 25.2 'C aw= 0.299 H2O= 19 ppm RS= 29.9 %
```

## **Troubleshooting Commands**

## **Display the Currently Active Errors**

Use the **ERRS** command to display the currently active transmitter error states. Possible errors and their causes are listed in Table 11 on page 52.

ERRS<cr>

Example:

**errs** No errors

## **Test Analog Outputs**

The operation of the analog outputs can be tested with the **ATEST** command by forcing the output to a given value which can then be measured with calibrated multimeter. The command uses the currently selected analog output types for the channels (voltage or current) so you do not have to specify the unit.

Before testing, you can verify the currently set analog output modes using the **AMODE** command. After testing the output, give the **ATEST** command again to exit the test mode.

ATEST [*xxx yyy*]<cr>

where

XXX	=	Channel 1 output value (V or mA)
ууу	=	Channel 2 output value (V or mA)

The output shows the test values of the analog channels, and diagnostic information that may be useful to Vaisala Service if there is a problem with the analog outputs.

Example:

atest 1 15	
1.00	2660
15.00	19425
atest	
0.00	79
0.00	20110

## **Other Commands**

## **Opening the Transmitter in POLL Mode**

Use the **OPEN** command to connect to a transmitter that is in POLL mode.

OPEN [aaa]<cr>

where

aaa =  $address (0 \dots 255)$ 

Example:

open 0
MMT162 0 line opened for operator commands

## Closing the Connection to a Transmitter in POLL Mode

The CLOSE command closes the connection to the transmitter.

CLOSE<cr>

Example:

**close** line closed

## **Display Command List**

Use the **HELP** command to list the available commands.

HELP<cr>

Example:

#### help

? ACAL ADDR ADJD AERR ALARM AMODE AOVER ASEL ATEST CDATE CLOSE CRH СТ CTEXT ERRS FILT FORM FRESTORE HELP INTV L LED OIL OILI OPEN PCOMP PRES R RESET SDELAY SEND SERI SMODE UNIT

## **Show User Calibration Coefficients**

Use the L command to view the current user calibration coefficients on the serial line. This command is useful for checking if non-factory adjustments have been applied for humidity and temperature measurement.

L<cr>

The output values are as follows:

- RH offset and gain: corrections to RH measurement. These values change when you calibrate and adjust the humidity measurement.
- T offset and gain: corrections to T measurement. These values change when you calibrate and adjust the temperature measurement.

For more information on how the adjustments affect these coefficients, see section Adjustment Points on page 55.

Example (shows default values, no user adjustment done):

1 RH offset : 0.0000000E+00 RH gain : 1.0000000E+00 T offset : 0.0000000E+00 T gain : 1.0000000E+00

## Set User Calibration Coefficients

Use the **LI** command to enter values for offset and gain coefficients for on the serial line. Useful for restoring the factory defaults, or some earlier state of user adjustment.

**CAUTION** Use this command only to restore values you have previously written down based on the output from the L command, or to restore the default offset and gain.

LI<cr>

After you enter the command, you will be prompted to enter new values for the coefficients. The default offset is zero (0), default gain is one (1).

Example (shows user adjusted offset values, overwrites them with 0):

li
RH offset : -4.35084105E-04 ? 0
RH gain : 1.0000000E+00 ?
T offset : -1.62982941E-02 ? 0
T gain : 1.0000000E+00 ?

## **Reset Transmitter**

When the **RESET** command is given, the transmitter will restart as if it had just been powered on. All transmitter settings are retained. The serial line mode of the transmitter will be set to the mode that was set using the **SMODE** command.

RESET<cr>

## **Restore Factory Settings**

Use the **FRESTORE** command to restore the factory settings to the transmitter. All user settings will be lost.

FRESTORE<cr>

## **Modbus Communication**

The Modbus variant used in MMT162 communication is Modbus RTU. Below is an example of a request to read the currently measured temperature value from transmitter with address 240, and the response from the transmitter.

Request to read registers 3 and 4 (currently measured value of T):

F0h	03h	00h	02h	00h	02h	70h	EAh
transmitter	function	address of		number of		CRC check	
address	code	first register		registers to			
				rea	ad		

Response as IEEE 754-2008 binary32 (41BBA77Ch = 23.4568 °C):

F0h	03h	04h	A7h	7Ch	41h	BBh	88h	73h
transmitter	function	number of	data	from	data	from	CRC	check
address	code	data bytes to follow	first re	egister	sec regi			

For a list of available Modbus registers, see Appendix A Modbus Reference on page 70.

## Accessing Serial Port Command Interface from Modbus Mode

You cannot change configuration settings (other than Modbus address) while the device is in the Modbus mode. To use the configuration commands on a Modbus-enabled device:

- 1. Connect the USB service cable to the PC and install the driver, if necessary.
- 2. Open the terminal program and open a connection to the corresponding COM port using settings 19200, 8, N, 1, no flow control.
- 3. Plug the service cable to the connector II of the instrument.
- 4. In less than three seconds, send a hash character (#) and carriage return (Enter) to the device using the terminal program. The device is now ready for configuration commands. The Modbus mode is restored on next power-up unless Modbus is disabled with command **SMODE**.

For example, if you want to deactivate the Modbus mode on a MMT162 device, follow the procedure above and deactivate the Modbus mode with command **SMODE STOP**. On subsequent power-ups, the serial command interface will be activated.

#### **Configuration Commands Related to Modbus**

In addition to enabling the Modbus protocol in the device, Modbus over RS-485 needs the following software settings: serial bit rate, parity, number of stop bits, and Modbus device address.Use the service commands listed in Table 10 below to configure the Modbus RTU using the USB service cable.

Service Command Description **SMODE MODBUS** Enable Modbus communication protocol SERIbp8s Change baud rate and parity b = baud rate (9600, 19200, 38400, 57600, 115200) p = parity (E, N, or O)8 = number of data bits must be 8 s = number of stop bits (2 if parity is N, 1 otherwise\*) Bit rates less than 9600 b/s are not supported with Modbus. ADDR a Set Modbus address a = new address (0...255)\*\* SDELAY d Add extra Modbus response delay\*\*\*

Table 10Configuration Commands for Modbus RTU

\* Modbus specification defines that two stop bits must be used if parity is N.

\*\* Setting address to zero switches the instrument offline from the Modbus bus. Addresses 248 ... 255 are not supported by the Modbus standard but MMT162 works with them.

d = new delay in units of 1/250 seconds (0...255)

\*\*\* Extra response delay can be used, for example, to avoid problems caused by direction-switching delays in bus converters.

**NOTE** The instrument must be switched off and on before the configuration changes made with the service cable take effect.

## ppm Conversion

## MMT162 ppm Conversion for Transformer Oils

Traditionally, moisture in transformer oil is measured by using ppm units. The ppm output shows the average *mass concentration of water* in oil.

The moisture and temperature transmitter MMT162 has an option for ppm-output provided that this has been notified when placing the order for the transmitter. Vaisala has this conversion readily available for mineral transformer oils.

## **Conversion Model with Average Coefficients**

The conversion model of the MMT162 is based on the average water solubility behaviour of transformer oils. The ppm-output is calculated as follows:

 $ppm = aw \times 10^{(A/(T+273.16)+B)}$ 

where

aw = water activity A,B= coefficients (average/oil-specific) T = temperature (°C)

Generally, measurements with MMT162 give accuracy better than 10 % of the reading. If additional accuracy is needed, refer to section Conversion Model with Oil-specific Coefficients below.

### **Conversion Model with Oil-specific Coefficients**

For additional accuracy, oil-specific conversion model can be used both for mineral and silicon based oils. An oil sample has to be sent to Vaisala for modelling. As a result, the specific coefficients (A and B) for the transformer oil are determined by Vaisala. For additional information, please contact Vaisala.

The determined coefficients of the transformer oil can be programmed to the MMT162 by Vaisala or by a user according to the instructions presented in this chapter.

```
NOTE Conversion model with oil-specific coefficients is always needed for silicone based oils.
```

## **Setting Oil Coefficients Using Serial Line**

If the ppm conversion and oil-specific coefficients have been programmed at Vaisala, you do not have to set the conversion coefficients.

If you have defined the coefficients or separately received from Vaisala the oil-specific coefficients A and B, related to your own oil type, the coefficients can be set to the software of MMT162 by using serial line.

#### OIL

Use the serial line command **OIL** to display oil-specific parameters for ppm conversion. With **OILI** command you can set new oil parameters.

#### Example:

oil		
Oil[0]	:	-1.66269994E+03
Oil[1]	:	7.36940002E+00
Oil[2]	:	0.0000000E+00

```
where
```

Oil [0]	corresponds to parameter .	A

- Oil [1] corresponds to parameter B
- Oil [2] Corresponds to parameter C

## Determination of Oil-Specific Coefficients

The equation of the ppm calculation is:

#### $ppm = aw \times 10^{(B+A/T)}$

With the following procedure the coefficients A and B can be defined for the equation:

#### $LOG(PPM_{sat}) = B + A/T$

Equipment needed:

- Apparatus for determining water content ( for example, coulometric titrator and e.g. magnetic stirrer.)
- Oil test station:
  - a temperature test chamber.
  - a suitable container (for example, a conical 1 L flask) sealed by PTFE stopper with an inlet for a moisture probe.
  - a MMT162 transmitter by Vaisala.
  - a magnetic stirrer.

Procedure:

- 1. Define the water content of the oil sample with the titration. Use the oil moisture level that is close to real conditions in the process.
- 2. Measure the water activity of this sample with MMT162 at two temperatures that differ at least 20 °C.

**NOTE** The sample has to be sealed very carefully. Contact with ambient air will change the water content.

NOTEIf the oil sample is very dry and the temperatures are close to each<br/>other, it may cause inaccuracy to the calculation model. In order to<br/>get the best possible performance it is recommended to use oil<br/>conditions that represent real conditions in application.<br/>Recommended values for sample are aw approx. 0.5 at 20 °C.

3. Define the correlation between aw, T and PPM (w/w) from the measured values. Calculate A and B according to the following example.

$$A = \frac{LOG(PPM_{sat}[T2]) - LOG(PPM_{sat}[T1])}{1/(T2) - 1/(T1)}$$

$$B = LOG(PPM_{sat}[T1]) - A/T1$$

Example (measured water content 213 ppm):

T (°C)	aw	ppm <sub>saturation</sub>
24.1	0.478	213/0.478 = 445.6067
57.6	0.188	213/0.188 = 1132.979

A = (LOG(1132.98)-LOG(445.607))/(1/(57.6+273.16)-1/(24.1+273.16)) = -1189.4581

Assumptions:

The isoterm of water activity versus water concentration is linear and the solubility curve has the form of the given equation.

## CHAPTER 5 MAINTENANCE

This chapter provides information that is needed in basic maintenance of the product.

## Cleaning

Clean the transmitter enclosure with a soft. lint-free cloth moistened with mild detergent.

Clean the sensor before storing the MMT162 probe and before calibration. For cleaning the the probe you need instrument air and heptane ( $C_7H_{16}$ ) liquid. If heptane is not available, you can also use diesel oil or petrol. Dry with instrument air to prevent oxidation of the oil on the sensor. The oxidation of the oil on the sensor can cause extended response times or drifting.

- 1. Blow the probe head (with filter) with instrument air to remove the remains of oil.
- 2. Immerse the probe head into heptane liquid and rinse out the oil (for one minute maximum).
- 3. Dry the probe head with instrument air. In case you are going to calibrate the probe, remove the filter and dry the sensor with instrument air. Check that the sensor looks clean.

**NOTE** Do not immerse the sensor in any polar solvents, for example ketones or alcohols.

## **Changing the Filter**

- 1. Remove the filter from the probe.
- 2. Install a new filter on the probe. When using the stainless steel filter (for oil and fuel cell), take care to tighten the filter properly (recommended force 130 Ncm).

New filters can be ordered from Vaisala, see section Spare Parts and Accessories on page 67.

## **Changing the Sensor**

If you need to change the sensor on your MMT162, contact a Vaisala Service Center. See section Product Returns on page 53.

### **Error States**

MMT162 has the following states that indicate a problem with the probe:

- Analog 4 20 mA current output at 0 mA
- Analog voltage output at 0 V
- Serial line outputs asterisk characters (\*\*\* \*\*)

The asterisk characters on the serial line may also appear during the startup procedure.

You can also check the error message via the serial interface by using the **ERRS** command. In case of constant error, please contact Vaisala; see section Technical Support on page 53.

Error Message	Action
Voltage error	Internal error or invalid supply voltage.
T meas error	Internal error, can be caused by
	damage to the temperature sensor.
F meas error	Internal error, can be caused by
	damage to the HUMICAP® sensor.
Voltage too low error	Supplied operating voltage is too low
	for reliable operation.
Voltage too low for mA output	Supplied operating voltage is too low
	for reliable operation of the analog
	current output.
Voltage is too low for V output	Supplied operating voltage is too low
	for reliable operation of the analog
	voltage output.
Program flash check sum error	Internal error
Parameter check sum error	Internal error
INFOA check sum error	Internal error
SCOEFS check sum error	Internal error
CURRENT check sum error	Internal error

Table 11Error Messages

## **Unknown Serial Settings**

If you are not sure what the current serial settings of your transmitter are, follow the steps below to connect to the transmitter. This procedure assumes you have the USB service cable available.

For more information on the USB service cable and the PuTTY terminal application, see section Serial Communication on page 22.

- 1. Connect the USB service cable to your PC, but do not connect it to the transmitter yet.
- 2. Start a terminal application and open a terminal session using the default serial settings of 19200 8 N 1.
- 3. Plug the USB service cable into the transmitter, and quickly send at least one hash character # to the serial line:
  - #
- 4. The normal startup of the transmitter is now interrupted, and the transmitter is available for commands with the default serial settings. You can now check the transmitter's information by issuing the ? command:

?

The transmitter's currently stored serial settings are visible on the line marked **Baud P D S**.

## **Technical Support**

For technical questions, contact the Vaisala technical support by e-mail at <u>helpdesk@vaisala.com</u>. Provide at least the following supporting information:

- Name and model of the product in question
- Serial number of the product
- Name and location of the installation site
- Name and contact information of a technically competent person who can provide further information on the problem.

## **Product Returns**

If the product must be returned for service, see <u>www.vaisala.com/returns</u>.

For contact information of Vaisala Service Centers, see <u>www.vaisala.com/servicecenters</u>.

## CHAPTER 6 CALIBRATION AND ADJUSTMENT

This chapter provides information that is needed in calibration and adjustment of the product.

# **NOTE** Calibration means comparing the instrument to a known reference, either against a second instrument or a known reference environment. Correcting the reading of the instrument so that is measures accurately is referred to as adjustment.

**NOTE** It is important to clean the sensor before calibration as the oily sensor can contaminate the salt bath and change the reference condition. For instructions, see section Cleaning on page 50.

The MMT162 is fully calibrated and adjusted as shipped from factory. The calibration interval depends on the application. You can perform a calibration to check that the transmitter is within its accuracy specification.

Performing an accurate calibration and adjustment takes some time and preparation. Instead of doing it yourself, you can also have a Vaisala service center calibrate and adjust your transmitter. For contact information, see section Product Returns on page 53.

## **Adjustment Points**

## **Humidity Measurement**

You can adjust the humidity measurement of the MMT162 in one or two points:

- One-point adjustment changes the RH measurement offset or gain. The transmitter determines which coefficient (offset or gain) should be changed based on the measured humidity.
- Two-point adjustment changes both offset and gain. The following requirements apply to the two points:
  - The adjustment must be started from the dry end of the measurement, with the point being < 50 %RH.
  - The second point must be > 50 %RH.
  - There must be at least 30 %RH difference between the points.

## **Temperature Measurement**

You can adjust the temperature measurement of the MMT162 in one or two points:

- One-point adjustment changes the T measurement offset.
- Two-point adjustment changes both offset and gain. The following requirements apply to the two points:
  - The adjustment must be started from the cool end of the measurement.
  - The second point must be at least 30 °C warmer than the first point.

## **Adjustment Procedures**

You can calibrate and adjust the MMT162 using Vaisala HUMICAP<sup>®</sup> hand-held moisture and temperature in oil meter MM70. See the following sections:

- Calibration and Adjustment Using MM70 and a Reference Probe below.
- Calibration and Adjustment Using MM70 and a Reference Environment on page 58.

Connecting to the serial interface using a computer and a terminal program allows you to perform calibration and adjustment tasks using serial commands. See the following sections:

- Relative Humidity Adjustment on Serial Line on page 61.
- Temperature Adjustment on Serial Line on page 63.

For checking and/or clearing the currently applied calibration coefficients on the serial line, see the following sections:

- Show User Calibration Coefficients on page 42.
- Set User Calibration Coefficients on page 42.

## Calibration and Adjustment Using MM70 and a Reference Probe

Required equipment:

- A fully charged MI70 indicator (the measurement display that is included in the MM70 package)
- A calibrated MMP70 series probe (included with the MM70 handheld meter)
- Connection cable for MM70 hand-held meter (219980)

You can check and adjust the MMT162 using the MM70 hand-held meter and a calibrated reference probe. You can perform this procedure while the MMT162 is installed in oil if the environment is stable enough.

- 1. Plug in the connection cable 219980 to port II of the MMT162, and the other end to port II of the MI70 indicator.
- 2. Connect the reference probe to port I of the MI70 indicator.
- 3. Insert the reference probe in the same environment as the MMT162.

- 4. Wait for 30 minutes for temperature and humidity to stabilize.
- 5. Turn on the MI70.
- 6. Select Display → Quantities and units from the menu of the MI70, and verify that measurements from both ports (I and II) are available. If the MMT162 is not detected, it may be because it is already powered up and using non-default serial line settings. Try the following steps:
  - a. Turn off the MI70.
  - b. Disconnect the cable from port I of the MMT162.
  - c. Turn on the MI70.
- 7. Select Functions → Adjustments (II) from the menu of the MI70 and press Start. Make sure the symbol for port II is shown after the word "Adjustments", as your reference probe may also be adjustable using the MI70.
- 8. The adjustment mode starts. Automatic power off is disabled while in adjustmend mode; press **OK** to acknowledge the message.
- 9. Select the parameter to calibrate and adjust (RH or T) from the list and press **Select**. This procedure is applicable for both parameters, but the following steps will assume you selected RH.
- 10. Check and adjust the environment settings of the reference probe if prompted by the MI70.
- 11. The adjustment mode now shows the value of the selected parameter from both instruments, and a delta parameter (for example,  $\Delta$ RH) that shows the difference between the two. The difference should be no greater than the combined measurement uncertainty of the MMT162 transmitter and the reference probe. Depending on the result, proceed as follows:
  - If the MMT162 transmitter is within its accuracy specification, there is no need to proceed with the adjustment. Select **Back** and **Exit** to leave the adjustment mode.
  - If adjustment is required, continue with the next step.
- 12. Select Adjust, and then select To same as RH (I).
- 13. The MI70 will ask **Do you really want to adjust**? Select **Yes**. MI70 shows the text **Adjustment done** and returns to the adjustment mode after a few seconds. Check the value of the delta parameter to verify that the adjustment has taken effect.
- 14. Select **Back** to return to the parameter selection screen.
- 15. Select a new parameter for adjustment and proceed as instructed above, or select **Exit** to leave the adjustment mode.

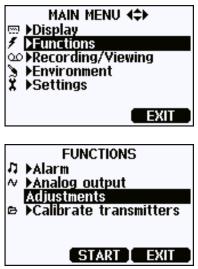
## Calibration and Adjustment Using MM70 and a Reference Environment

Required equipment:

- A fully charged MI70 indicator (the measurement display that is included in the MM70 package)
- Connection cable for MM70 hand-held meter (219980)
- One or two reference environments that fulfill the requirements listed in section Adjustment Points on page 55.

For example, you can use the Vaisala HMK15 humidity calibrator for a two-point humidity calibration and adjustment. Use the LiCl (11 %RH) and NaCl (75 %RH) salt solutions. You also need the special cover set for HMK15 (230914). For two-point calibrations using HMK15, use a dedicated cover for each salt chamber to avoid long stabilization times and possible contamination of the salt references.

- 1. Plug in the connection cable 219980 to port II of the MMT162, and the other end to port II of the MI70 indicator.
- 2. If any cable is connected to port I of the MMT162, disconnect it.
- 3. If the MMP70 probe is connected to the MI70 indicator, disconnect it.
- 4. Remove the filter from the MMT162 and insert it in the reference environment (for example, the LiCl (11 %RH) salt chamber).
- 5. Wait for 30 minutes for temperature and humidity to stabilize.
- 6. Turn on the MI70 indicator.
- 7. Select Functions  $\rightarrow$  Adjustments from the menu of the MI70 and press Start.



- 8. The adjustment mode starts. Automatic power off is disabled while in adjustmend mode; press **OK** to acknowledge the message.
- 9. Select the parameter to calibrate and adjust (RH or T) from the list and press **Select**. This procedure is applicable for both parameters, but the following steps will assume you selected RH.
- 10. The adjustment mode should now show a stable, unchanging RH value. The difference between the measured value and the reference humidity should be no greater than the combined measurement uncertainty of the MMT162 transmitter and the reference environment. Depending on the result, proceed as follows:
  - If the MMT162 transmitter is within its accuracy specification, there is no need to proceed with the adjustment. Select **Back** and **Exit** to leave the adjustment mode.
  - If adjustment is required, continue with the next step.



- 11. Press Adjust and select 1-point adjustment or 2-point adjustment.
- 12. Press **Ready** and enter the correct value (the reference value) for the parameter you are adjusting. Press **OK** when done, and **YES** when asked if you really want to adjust.
- 13. You have now entered the first adjustment point. If you selected **1point adjustment**, you will see the text **Adjustment done**. You have now completed the 1-point adjustment. Select **Back** and **Exit** to leave the adjustment mode.

If you are doing a **2-point adjustment**, the indicator shows the screen for the second reference point. Continue with the next step.

If something went wrong with the adjustment, check that your reference environment fulfills the requirements listed in section Adjustment Points on page 55, and that the measurement had properly stabilized. Retry the adjustment after checking.

14. Transfer the MMT162 to the second reference environment (for example, the NaCl (75 %RH) salt chamber).

- 15. Wait for the measured value to stabilize and press **Ready**. Enter the correct value of the reference point. Press **OK** when done, and **YES** when asked if you really want to adjust.
- 16. You will see the text **Adjustment done**. You have now completed the 2-point adjustment. Select **Back** to return to the parameter selection screen, and **Exit** to leave the adjustment mode.
- 17. Remove the MMT162 from the reference environment and reattach the filter.

## **Relative Humidity Adjustment on Serial Line**

Required equipment:

- Computer with
  - Windows operating system
  - Terminal application
  - Free USB port
  - Driver for Vaisala USB cable installed
- USB serial interface cable (219690)
- One or two humidity references that fulfill the requirements listed in section Adjustment Points on page 55.

For example, you can use the Vaisala HMK15 humidity calibrator for a two-point humidity calibration and adjustment. Use the LiCl (11 %RH) and NaCl (75 %RH) salt solutions. You also need the special cover set for HMK15 (230914). For two-point calibrations using HMK15, use a dedicated cover for each salt chamber to avoid long stabilization times and possible contamination of the salt references.

- 1. If any cable is connected to port I of the MMT162, disconnect it.
- 2. Remove the filter from the MMT162 and insert the sensors into the humidity reference. If you are starting a two-point calibration, start with the dry end reference. If you are using the HMK15, start with the LiCl salt bath (11 %RH).
- 3. Wait at least 30 minutes for the humidity to stabilize.
- 4. Connect the MMT162 to a PC, see section Serial Communication on page 22. Then open a terminal program.
- 5. Enter the **1** command to view the currently active calibration coefficients. For more information, see section Show User Calibration Coefficients on page 42.
- 6. Enter the **crh** command and press Enter: crh
- 7. Type **c** and press Enter to update the reading and verify that the reading has stabilized:

```
RH : 11.9206 1. ref ? c
RH : 11.9206 1. ref ?
```

8. When the reading is stable, enter the reference humidity after the question mark and press Enter:

RH : 11.9191 1. ref ? **11.3** Press any key when ready ...

- 9. The first adjustment point is now stored. Now you have to choose:
  - Press Enter **once** to continue to the next step of the procedure (two-point adjustment). The adjustment sequence continues to the second reference point:

RH : 11.3143 2. ref ?

- Press Enter **twice** to exit the procedure now, completing a one-point adjustment only. The adjustment sequence ends with the text **OK**. Continue to step 12.

OK

- 10. Transfer the probe to the second humidity reference. If you are using the HMK15, use the NaCl (75 %RH) salt bath. Do not disconnect the cable from the transmitter or the adjustment sequence will be interrupted.
- 11. Wait for the humidity to stabilize. Type **c** and press Enter to update the reading and verify that the reading has stabilized:

RH : 68.0236 2. ref ? **c** RH : 71.1774 2. ref ?

12. When the reading is stable, enter the reference humidity after the question mark and press Enter:

```
RH : 74.3220 2. ref ? 75.5
OK
```

- 13. The RH adjustment is now complete. Enter the 1 command to verify that the calibration coefficients for RH have changed.
- 14. Remove the MMT162 from the reference environment and reattach the filter.

## **Temperature Adjustment on Serial Line**

Required equipment:

- Computer with
  - Windows operating system
  - Terminal application
  - Free USB port
  - Driver for Vaisala USB cable installed
- USB serial interface cable (219690)
- One or two temperature references that fulfill the requirements listed in section Adjustment Points on page 55.
- 1. If any cable is connected to port I of the MMT162, disconnect it.
- 2. Remove the filter from the MMT162 and insert the sensors into the temperature reference. If you are starting a two-point calibration, start with the lower temperature reference.
- 3. Wait at least 30 minutes for the temperature to stabilize.
- 4. Connect the MMT162 to a PC, see section Serial Communication on page 22. Then open a terminal program.
- 5. Enter the **1** command to view the currently active calibration coefficients. For more information, see section Show User Calibration Coefficients on page 42.
- 6. Enter the **ct** command and press Enter:
- 7. Type **c** and press Enter to update the reading and verify that the reading has stabilized:

T : 22.3106 1. ref ? **c** T : 22.3251 1. ref ?

8. When the reading is stable, enter the reference temperature after the question mark and press Enter:

T : 22.3261 1. ref ? **22.3** Press any key when ready ...

- 9. The first adjustment point is now stored. Now you have to choose:
  - Press Enter **once** to continue to the next step of the procedure (two-point adjustment). The adjustment sequence continues to the second reference point:

```
T : 22.3009 2. ref ?
```

- Press Enter **twice** to exit the procedure now, completing a one-point adjustment only. The adjustment sequence ends with the text **OK**. Continue to step 12.

OK

- 10. Transfer the probe to the second temperature reference. Do not disconnect the cable from the transmitter or the adjustment sequence will be interrupted.
- 11. Wait for the temperature to stabilize. Type **c** and press Enter to update the reading and verify that the reading has stabilized:

```
T : 54.1243 2. ref ? c
T : 54.1442 2. ref ?
```

12. When the reading is stable, enter the reference temperature after the question mark and press Enter:

```
T : 55.1841 2. ref ? 55.1
OK
```

- 13. The temperature adjustment is now complete. Enter the **1** command to verify that the calibration coefficients for T have changed.
- 14. Remove the MMT162 from the reference environment and reattach the filter.

## **Analog Output Adjustment**

In the analog output calibration the analog output is forced to the following values:

- Current output: 2 mA and 18 mA.
- Voltage output: 10 % and 90 % of the range.

Connect MMT162 to a calibrated current/voltage meter in order to measure either current or voltage depending on the selected output type.

To calibrate analog output, see section Calibrate Analog Output on page 35.

## CHAPTER 7 **TECHNICAL DATA**

This chapter provides the technical data of the product.

## **Measured Parameters**

#### Water activity

Measurement range	0 1 (@-40 +180 °C/ -40 +356 °F)
Accuracy (including non-linearity, hyste	resis and repeatability)
When calibrated against salt solutions (A	ASTM E104-85):
0 0.9	$\pm 0.02$
0.9 1.0	$\pm 0.03$
Response time in oil flow (typical)	
with stainless steel filter	< 1 min. (dry-wet)
Sensor	HUMICAP®
Temperature	
Measurement range	-40 +80 °C (-40 +176 °F)
Accuracy at +20 °C (+68 °F)	± 0.2 °C (± 32.36 °F)
Typical temperature dependence of	
electronics	± 0.005 °C/°C (± 0.003 °F/°F)
Sensor	Pt100 RTD Class F0.1 IEC 60751

## **Operating Environment**

Operating temperature Pressure range metal version plastic version Complies with EMC standard Oil flow

## Inputs and Outputs

Minimum operating voltage 22...28 VDC with current output with voltage output 16...28 VDC with RS-485 14...28 VDC Supply current normal measurement External load for current output max. 500  $\Omega$ min. 10 k $\Omega$ voltage output Analog outputs (2 standard) current output voltage output Accuracy of analog outputs at 20 °C Temperature dependence of the analog outputs current voltage Digital output **RS-485** 

### **Mechanics**

Interface cable connector

Probe cable diameter Probe cable lengths shielded cables 90° angle cable LED cable Housing material metal plastic Housing classification Mechanical connections Option 1 Option 2 Weight Metal with ISO thread 200 g 200 g Metal with NPT thread Plastic with ISO thread 65 g

-40 ... +60 °C (40 ... +140°F)

up to 200 bar up to 40 bar EN61326-1: Industrial environment some flow recommended

20 mA + load current

0 ... 20 mA, 4 ... 20 mA 0 ... 5 V, 0 ... 10 V  $\pm 0.05$  % full scale

 $\pm 0.005$  %/°C full scale

M8 series 4-pin (male) with plug (female) with straight or 90° angle connector 5.5 mm

0.32 m, 3 m, 5 m and 10 m 2 m and 5 m3 m

AISI 316L PPS + 40% GF IP 65 (NEMA 4)

ISO G1/2" NPT 1/2"

## **Spare Parts and Accessories**



Information on spare parts, accessories, and calibration products is available online at www.vaisala.com and store.vaisala.com.

Description	Order code
Connection cable for MM70	219980
USB serial interface cable	219690
CH1 signal + Ch2 LED cable, M8 threaded	MP300LEDCBL
connector	
Sealing ring set (copper) ISO G1/2, 3 pieces	221524SP
Sealing ring set (U-seal) ISO G1/2, 3 pieces	221525SP
Protection plug for connector	218675
ISO 1/2" plug	218773
NPT 1/2" plug	222507
110 240 VAC external power supply	POWER-1
Calibration adapter for HMK15	211302SP
Special cover set for HMK15	230914
Filters	
Stainless steel grid filter (with 3 mm holes)	225356SP
Stainless steel grid filter for high flow	221494SP
(with 2 mm holes, for > 1 m/s flow)	
Analog/RS-485 output cables	
0.32 m (1 ft) shielded cable, M8 threaded	HMP50Z032
connector	
3 m (9.8 ft) shielded cable, M8 threaded	HMP50Z300
connector	
5 m (16.4 ft) shielded cable, M8 threaded	HMP50Z500
connector	
10 m (32.8 ft) shielded cable, M8 threaded	HMP50Z1000
connector	
2 m (9.8 ft) cable, 90° angle connector	221739
5 m (16.4 ft) cable, 90° angle connector	221740
Sampling cells (available only for ISO	
G1/2")	
Sampling cell	DMT242SC
Sampling cell with 1/4" male Swagelok	DMT242SC2
connectors	

## **Dimensions in mm (inches)**

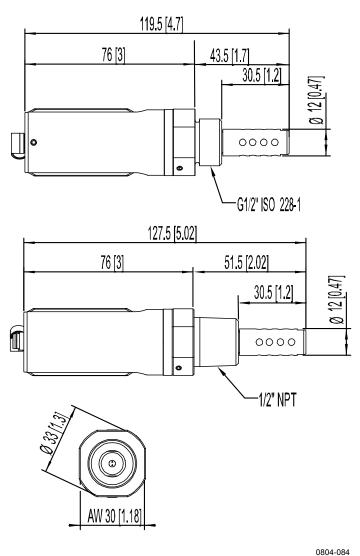


Figure 13 Metal Housing Transmitter Dimensions

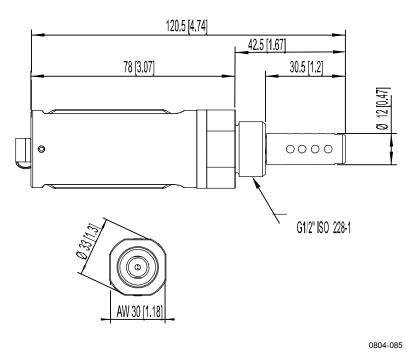


Figure 14 Plastic Housing Transmitter Dimensions

# APPENDIX A MODBUS REFERENCE

This appendix describes the Modbus protocol implementation of the MMT162 transmitter.

## **Default Communication Settings**

Table 12 below shows the default communication settings when Modbus is enabled at the factory. For information on how to configure the communication settings using serial line commands, see Table 10 on page 45.

Setting	Default Value	
Bit rate	19200	
Number of data bits	8	
Parity	E	
Number of stop bits	1	
Device address	240	
Response delay	0	
Communication mode	MODBUS	

Table 12Default Communication Settings

NOTE

You can also change device address with Modbus itself (register 1537).

## **Supported Modbus Functions**

Table 15 Supported Function Codes			
Function Code (decimal)	Function Code (hexadecimal)	Function Name (as defined by the specification)	Notes
3	03	Read Holding Registers	See Table 14 on page 71 for available registers.
16	10	Write Multiple Registers	See Table 14 on page 71 for available registers.
43 14	2B 0E	Read Device Identification	See Table 15 on page 72 for available device identification objects.

Table 13Supported Function Codes

**NOTE** After power-up, wait for five seconds before sending Modbus requests.

## **Modbus Register Map**

Logical Address (decimal)	PDU Address (hexadecimal)	Register Description		Data Format	Register Type	Notes
3	00 02	T (measured)	LSW MSW	32-bit	read-only	°C
4 29	00 03 00 1C	a (maasurad)	LSW	float 32-bit	road only	
30	00 1C	a <sub>w</sub> (measured)	MSW	float	read-only	
35	00 22	H <sub>2</sub> O (oil) (measured) *	LSW	32-bit	read-only	ppm
36	00 23		MSW	float		
513	02 00	Fault status		16-bit boolean	read-only	1 = no errors
516	02 03	Error Code	LSW	32-bit	read-only	0 = no errors
517	02 04		MSW	bit field		
785	03 10	Oil factor A (set value) *	LSW	32-bit	read/write	
786	03 11		MSW	float		
787	03 12	Oil factor B (set value) *	LSW	32-bit	read/write	
788	03 13		MSW	float		
1537	06 00	Address		16-bit integer	read/write	1255 (1 247 allowed in Modbus)

\* Availability of the register depends on the device model.

PDU address LSW MSW 16-bit integer 16-bit boolean 32-bit bit field 32-bit float read-only read/write Actual address bytes used in a Modbus Protocol Data unit. Least significant word (bits 15 ... 0). Most significant word (bits 31 ... 16). Numeric value in range 0 ... 65535. Numeric value, 0 or 1. 32 individual values, each 0 or 1. Floating point number encoded according to IEEE 754. Register value cannot be changed with Modbus functions. Register value can be changed with Modbus functions.

## **Device Identification Objects**

Table 15Device Identification Objects			
Object Id (decimal)	Object Id (hexadecimal)	Object Name (as defined by the specification)	Example
0	00	VendorName	Vaisala
1	01	ProductCode	MMT162
2	02	MajorMinorVersion	1.10
3	03	VendorUrl	http://www.vaisala.com
4	04	ProductName	Vaisala HUMICAP® Moisture and Temperature Transmitter for Oil MMT162
128	80	SerialNumber*	H0510038
129	81	CalibrationDate*	2014-08-21
130	82	CalibrationText*	Vaisala/HEL

\*Vaisala-specific device information object

NOTE

Both stream access and individual access to the device identification objects are supported.



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